

A radial scanning statistic for selecting space-filling designs in computer experiments

O. Roustant⁽¹⁾, J. Franco⁽²⁾, L. Carraro⁽³⁾, A. Jourdan⁽⁴⁾

(1) Ecole des Mines de St-Etienne – (2) Total – (3) Telecom Saint-Etienne – (4) EISTI Pau

MODA-9, Bertinoro, Italy



Framework

- Scientific framework
 - Keywords : Computer experiments, space-filling designs, dimension reduction, goodness-of-fit
- DICE Consortium (Sept. 2006 – Dec. 2009)
 - 5 industrial companies (TOTAL, Renault, IRSN, EDF, Onera : energy, automotive, nuclear and aerospace engineering)
 - 4 academic partners (Ecole des Mines de St-Etienne, Univ. Aix-Marseille, Univ. Joseph Fourier, Univ. Paris 11)
 - Objective : to study costly simulators
 - Web site : <http://www.dice-consortium.fr/>



Supplementary material

➔ *R* package "*DiceDesign*", available at <http://cran.r-project.org/>

A decorative wireframe sphere is located in the top-left corner of the slide. It is composed of a grid of lines forming a spherical shape, with a small dark dot at its center.

Outline

- ★ Motivations
- ★ The radial scanning statistic
- ★ Applications
 - ★ defect detection of SFDs
 - ★ selection of SFDs
- ★ Future research

A decorative wireframe sphere is located in the top-left corner of the slide.

Introduction - Framework

- Framework
 - **First investigation** of a costly **deterministic** simulator

$$y = f_{\text{sim}}(x_1, x_2, \dots, x_d)$$

- Cubic region $x=(x_1, \dots, x_d) \in \Omega = [-1, 1]^d$, $d=1, 2, \dots, 10, \dots, 20, \dots, 50, \dots$
- Objective
 - To study the phenomenon modeled by f_{sim} with few runs



Introduction - Assumptions

- Assumptions
 - ***Complexity of the phenomenon***
 - ⇒ Non-linearities of f_{sim}

- ***The effective dimension is $\ll d$***
 - ⇒ Only few factors are influent (sparsity)

$$f_{\text{sim}}(x) = g(x_{i_1}, \dots, x_{i_k}), \quad k \ll d$$

⇒ Only few principal components are influent

$$f_{\text{sim}}(x) = g(b_1'x, \dots, b_k'x), \quad k \ll d$$

- Remark
 - The latter is standard for dimension reduction
(as for Sliced Inverse Regression, see [Li, 1991])



Introduction - Consequences

- Consequences for designs
 - **Complexity of the phenomenon**
 - ⇒ Non-linearities of f_{sim} ⇒ **space-filling designs**

- **The effective dimension is $\ll d$**
 - ⇒ Only few factors are influent (sparsity)

$$f_{\text{sim}}(x) = g(x_{i_1}, \dots, x_{i_k}), \quad k \ll d$$

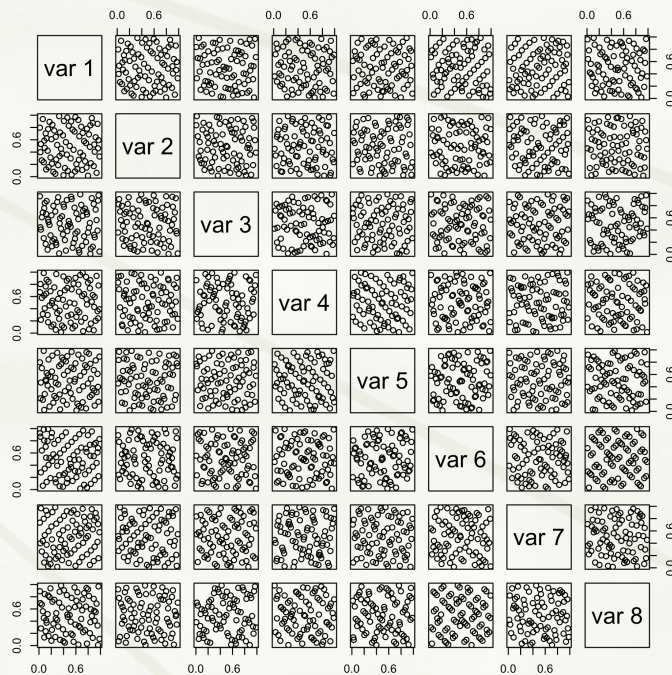
- ⇒ **space-filling of projections onto factorial subspaces**
- ⇒ Only few principal components are influent

$$f_{\text{sim}}(x) = g(b_1'x, \dots, b_k'x), \quad k \ll d$$

- ⇒ **space-filling of projections onto oblique subspaces**

Introductory example

- A 8D example
 - $f_{\text{sim}}(\mathbf{x}) = g(x_2, x_7)$, $d=8$
 - Common approach in practice : use a space-filling design (SFD), for instance a 80 points Sobol sequence



Introductory example

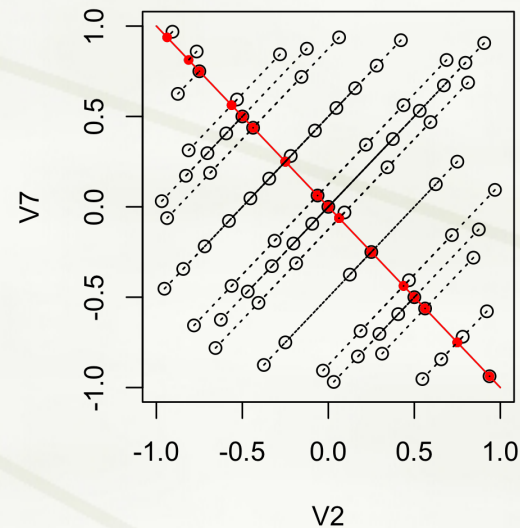
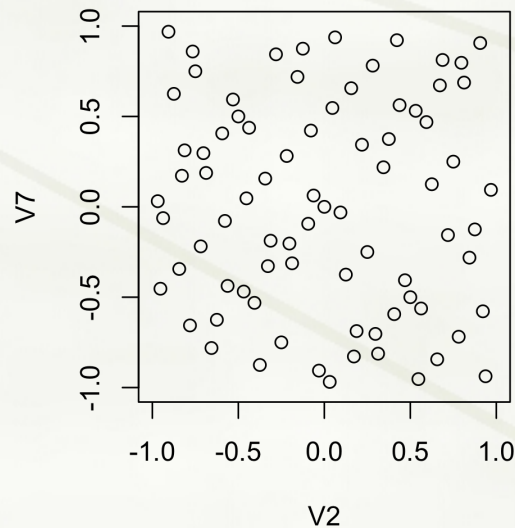
- A 8D example

- $f_{\text{sim}}(\mathbf{x}) = g(x_2, x_7)$, $d=8$
- Space-filling design : 80 points Sobol sequence

⇒ Space-filling is not so good in the subspace Vect(x_2, x_7)

⇒ If the code is a function of $x_2 - x_7$, only 16 different points !

loss of information





Introductory example

OBJECTIVE

- ⇒ To detect **automatically** such defects
- ⇒ To select space-filling designs that are still space-filling in projection onto **oblique** subspaces
 - ⇒ *more constraining than for LHDs or OAs*
 - ⇒ *to be precised in next slide*



Objective

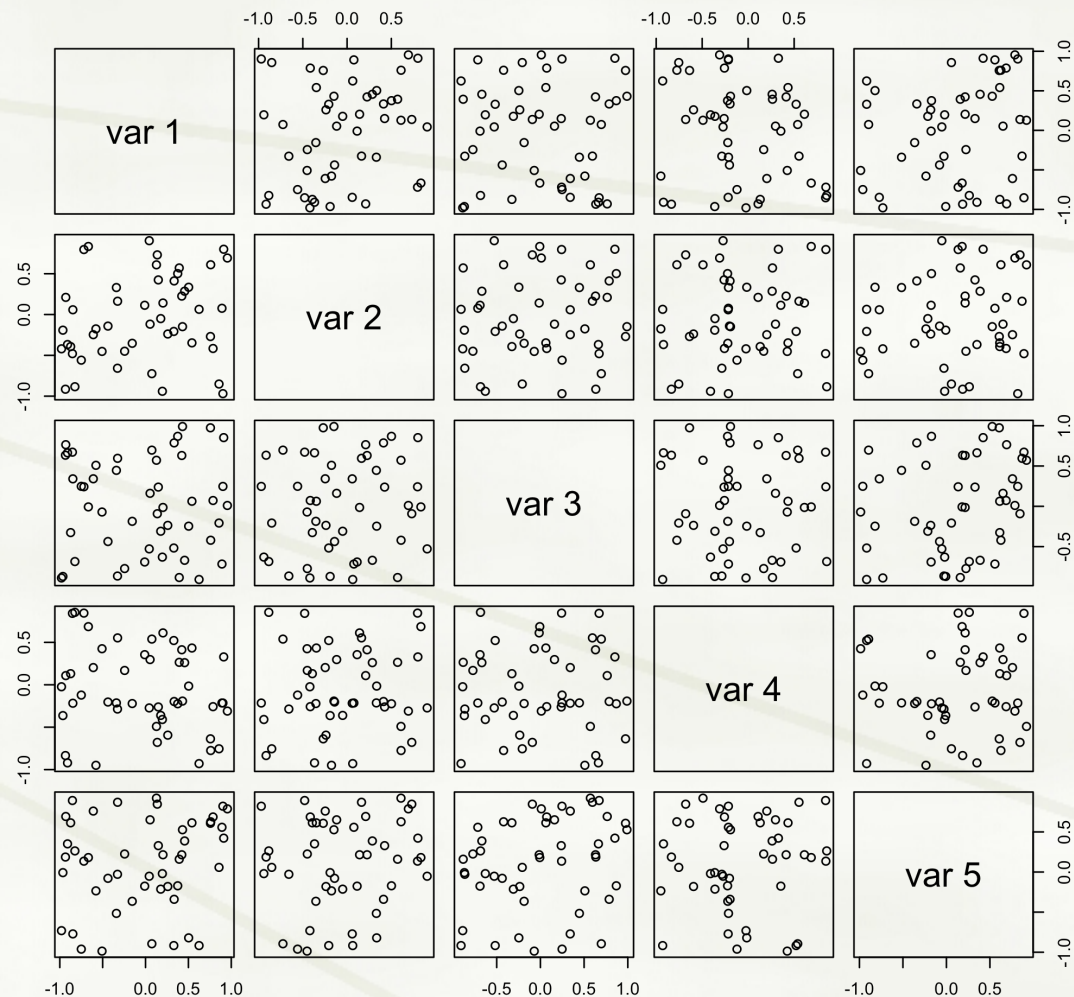
- Ideal objective:
 - There is a need to check good properties of projections onto any subspace spanned by $b_1'x, \dots, b_k'x$
- Revised ideal objective:
 - To check space-filling properties of the projections onto any (oblique) 1-dimensional axis [spanned by one $b'x$]
- Realization:
 - To check space-filling properties of the projections onto any 1-dimensional axis of the form :
 - $\beta_i x_i + \beta_j x_j$ 2D radial scanning statistic
 - $\beta_i x_i + \beta_j x_j + \beta_k x_k$ 3D radial scanning statistic

A good benchmark

- Uniform designs

- Advantage:
Space-filling
onto projections
- Main defaults :
clusters, holes

*A good SFD ?
advantages
without the
drawbacks of
uniform designs,
... / ...*

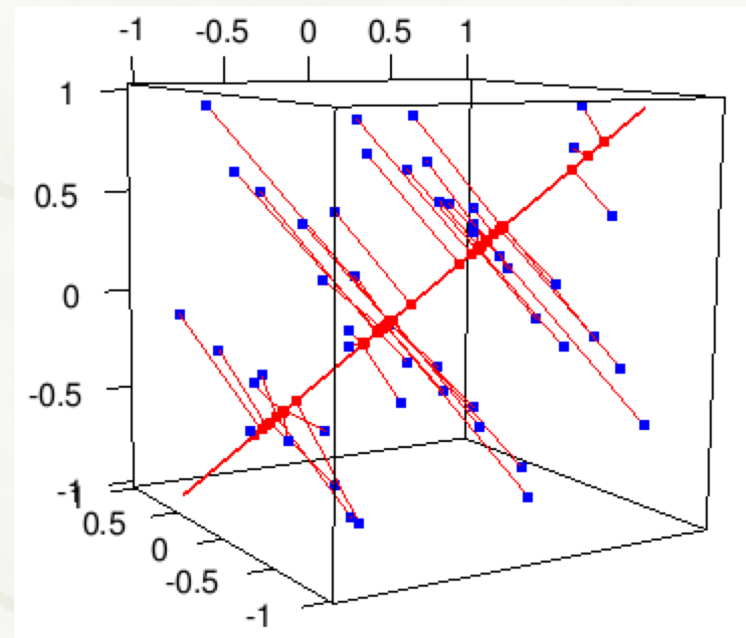
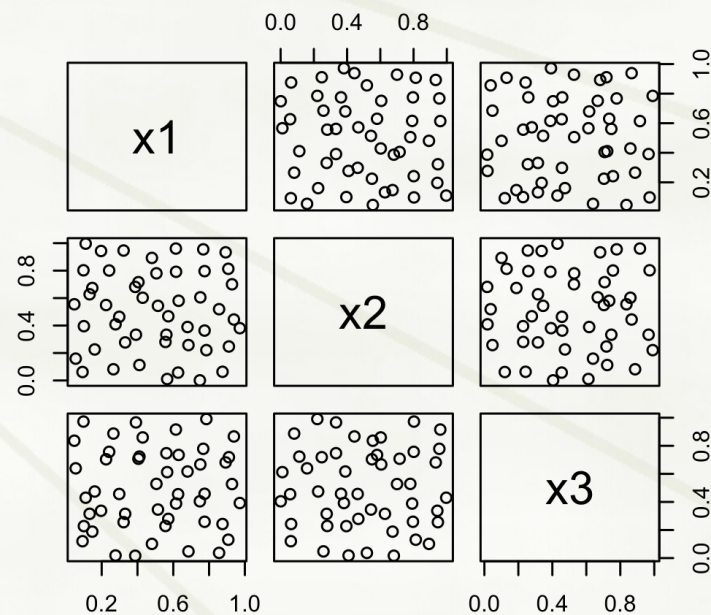


A good benchmark

A good SFD ?

*... and without
other drawbacks !*

A 3D randomized OA



A decorative wireframe sphere is located in the top-left corner of the slide. It is composed of a grid of lines forming a spherical shape, with a small dark dot at its center. The sphere is partially obscured by a white circular shape that frames the text below it.

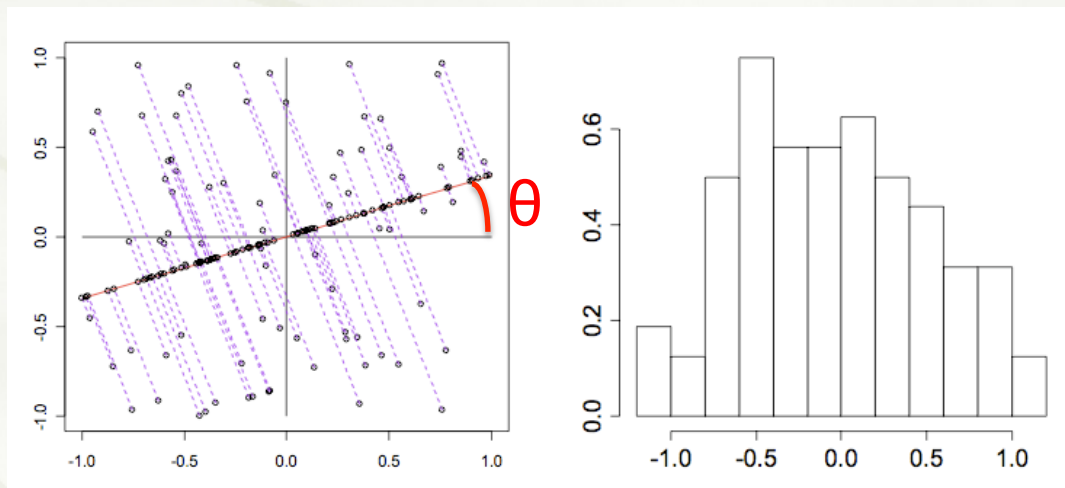
2nd part

★ The radial scanning statistic

The idea

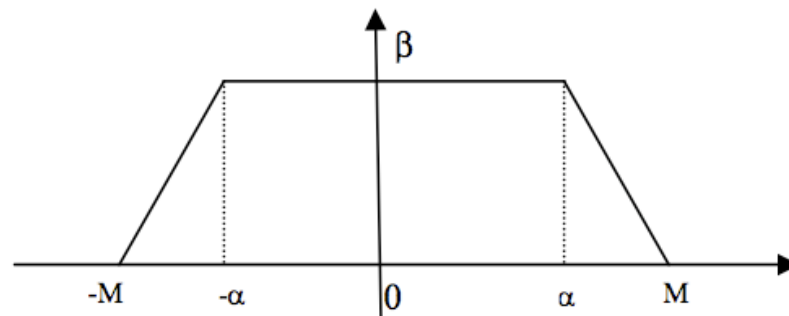
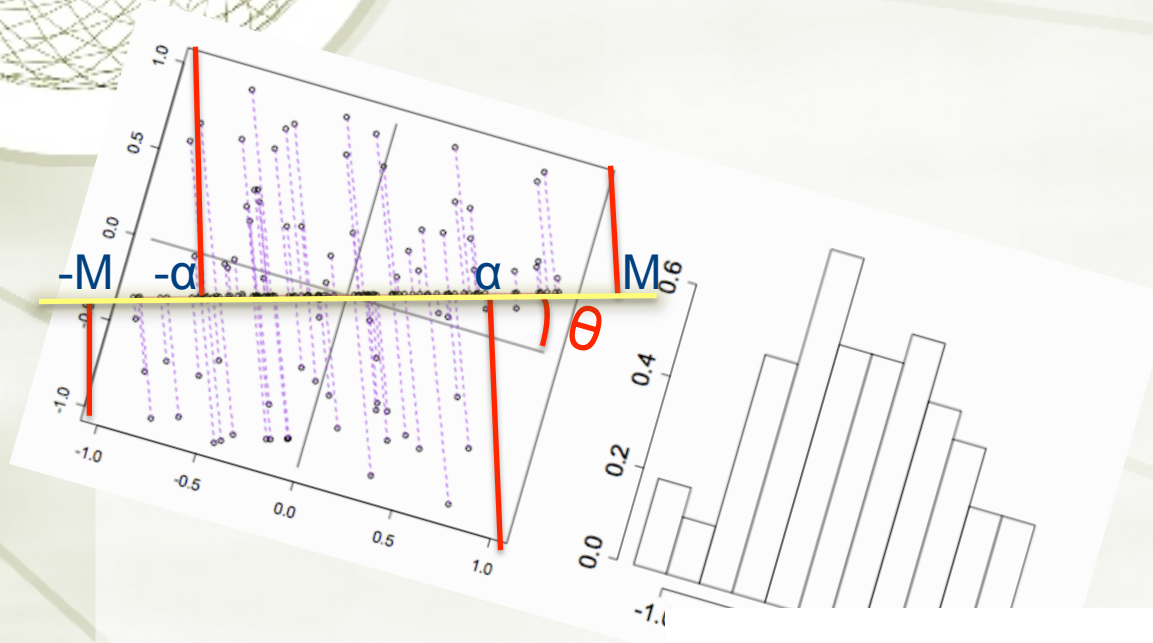
- Radial scanning – Case of a 2D subspace
 - Scan angularly the domain
 - For each radial direction, project orthogonally the design points

Are the projected points « **well** » distributed ?



Distribution of a sum of uniforms

- The distribution of $b'X$ is not uniform
 - Depends on the projections of the corners of $[-1,1]^d$ onto $\text{Vect}(b)$



avec :

$$M = |\cos\theta| + |\sin\theta|$$

$$\alpha = ||\cos\theta| - |\sin\theta||$$

$$\beta = \frac{1}{M + \alpha}$$

16



Distribution of a sum of uniforms

- Proposition (*Laplace, 18th Century ! – see a modern proof and discussion in [Elias and Shiu, 1987]*)

Proposition 1 *If X is a random vector uniformly distributed over the hypercube $\Omega = [-1, 1]^d$, and Z is the projection of X onto the straight line generated by a unitary vector a such that $a_j \neq 0, \forall j \in \{1, \dots, d\}$, then the cdf of Z is given by:*

$$F_Z(z) = \frac{1}{\prod_{j=1}^d 2a_j} \sum_{s \in \{-1, 1\}^d} \varepsilon(s) \frac{(x + \langle s, a \rangle)_+^d}{d!} \quad (2)$$

where $\varepsilon(s) = \prod_{j=1}^d s_j$, $\langle \cdot, \cdot \rangle$ is the usual scalar product and $y_+ = \max(y, 0)$. As a result, for a given axis, Z admits a piecewise linear density whose nodes correspond to the projections of the domain corners.



Mathematical formulation

- Assumption

- H_0 : « $x^{(1)}, \dots, x^{(n)}$ are a sample of the Uniform distribution »

- Formulation

- Let b be one direction in $[-1, 1]^d$
- Let F_b be the distribution of projections $b'X$, with $X \sim U([-1, 1]^d)$
- Question :

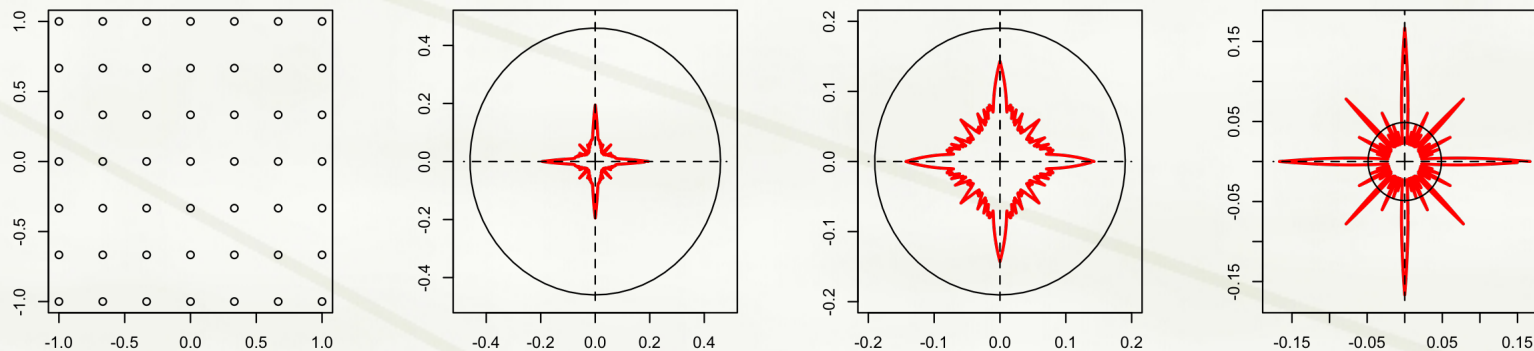
« Are the projections $b'x^{(1)}, \dots, b'x^{(n)}$ drawn from F_b ? »

- Equivalently : « Are $F_b(b'x^{(1)}), \dots, F_b(b'x^{(n)})$ *uniformly* distributed? »

⇒ Goodness-of-fit problem for the *uniform* distribution

Selecting a goodness-of-fit statistic

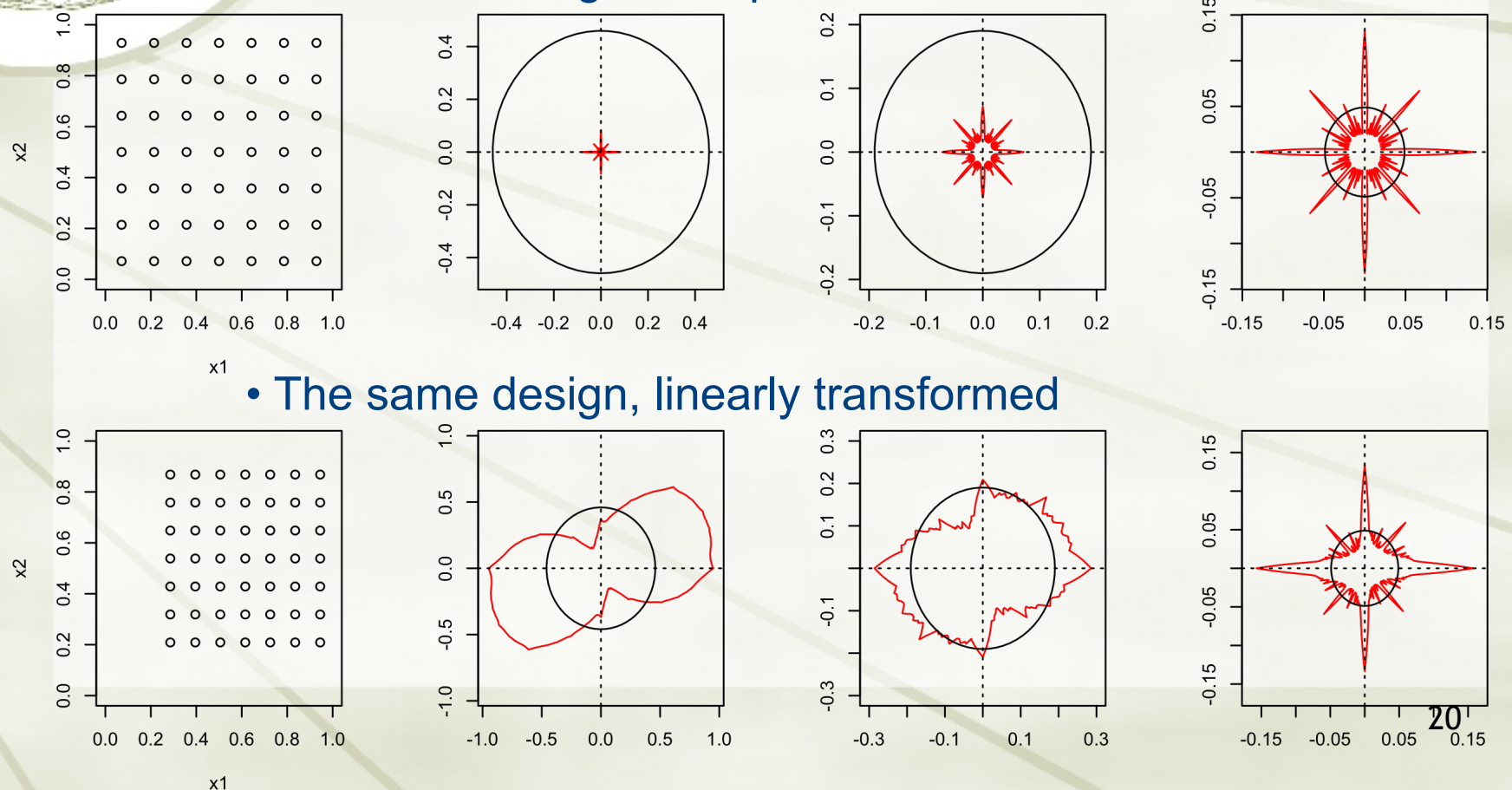
- Objective : to select a GOF statistic for the uniform distribution that detects **alignments** and **clustering**
 - Statistics based on CDFs (KS, CVM) usually fail, statistics based on « **spacings** » do it, such as Greenwood ([L'ecuyer, Simard, 2007])



2D RSS based on : CVM (left), KS (middle), Greenwood (right)

Robustness to domain misspecifications

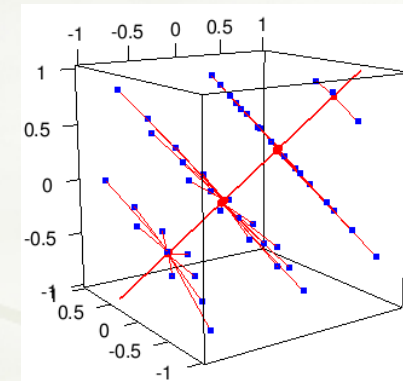
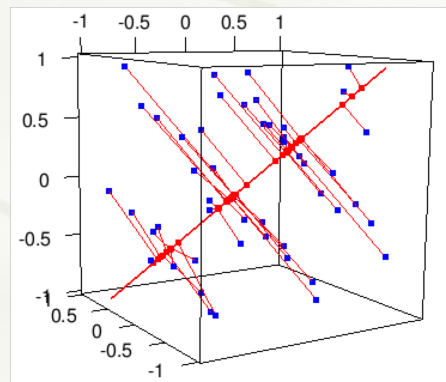
- Another feature of the statistics based on spacings
→ much less sensitive to domain misspecifications
- The same design, with points centered in each cell



Connected work

- Spectral test
 - Context : random numbers generators testing
 - Statistic : maximal distance of points contained in oblique parallel planes

➔ Detects **perfect** alignments (right), but not clusters (below)



• References

- Knuth, D. (1997). *The Art of Computer Programming, Volume 2: Seminumerical Algorithms*, 3rd edition. Addison-Wesley.
- Ripley, B. (1987). *Stochastic Simulation*. Wiley.

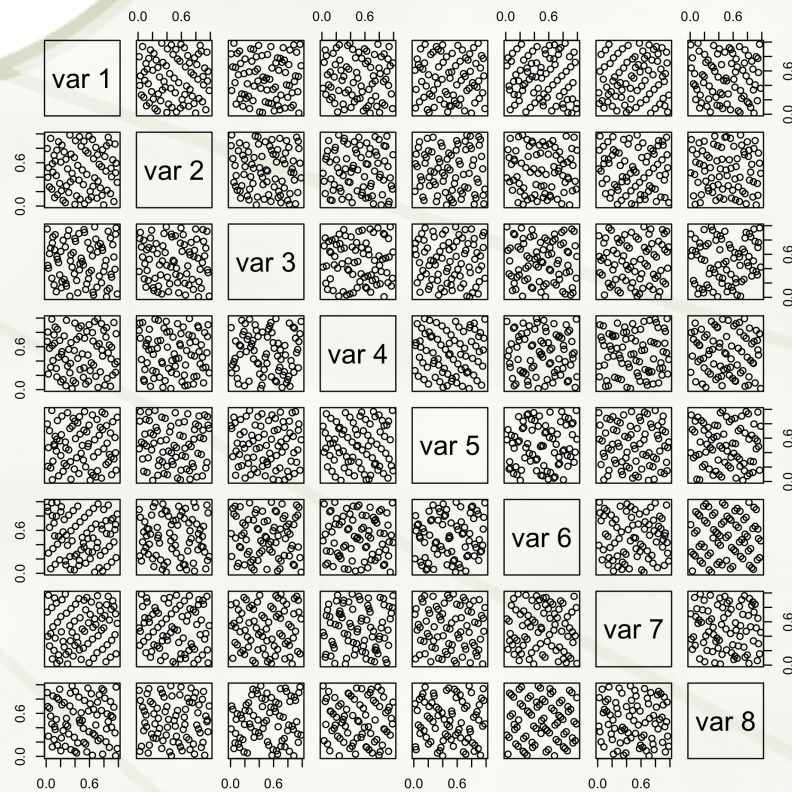
3rd part

A decorative wireframe sphere is located in the top-left corner of the slide. It is composed of a grid of lines forming a spherical shape, with a small dark dot at its center.

★ Applications

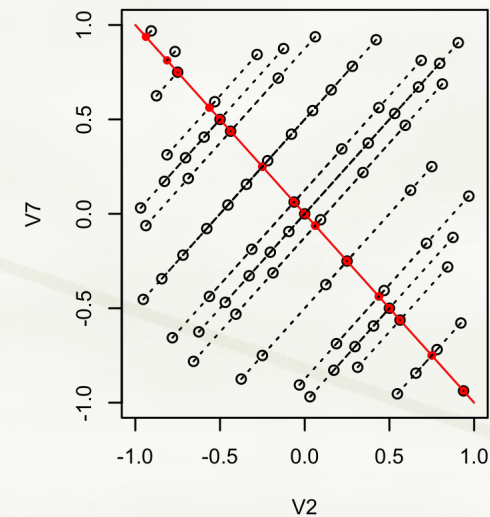
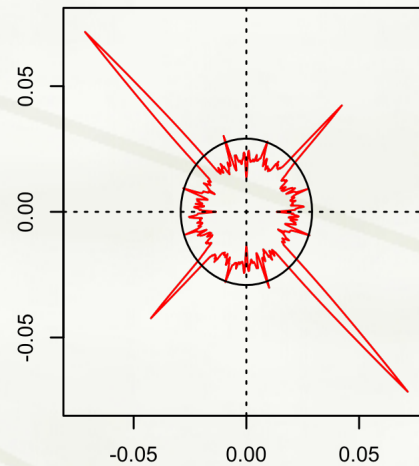
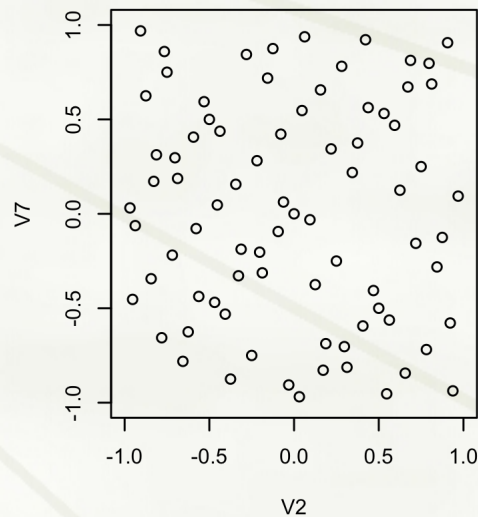
Defect detection

- Let us take again the 8D example
 - Space-filling design : 80 points Sobol sequence



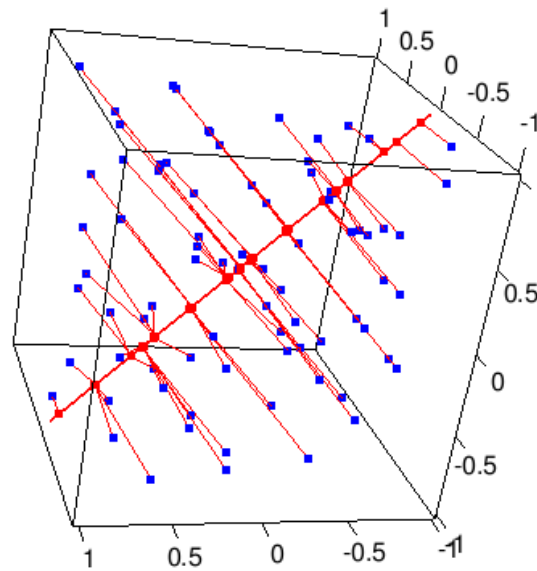
Defect detection

- 8D example (following) – 2D RSS
 - the worst case is for the pair of dimensions (2,7)
 - in this 2D factorial subspace, the worst direction is $\approx (1,-1)$



Defect detection

- 8D example (following) – 3D RSS
 - the worst case is for the triplet of dimensions (1,2,7)
 - in this 3D factorial subspace, the worst direction is $\approx (0,1,-1)$
(same problem detected)

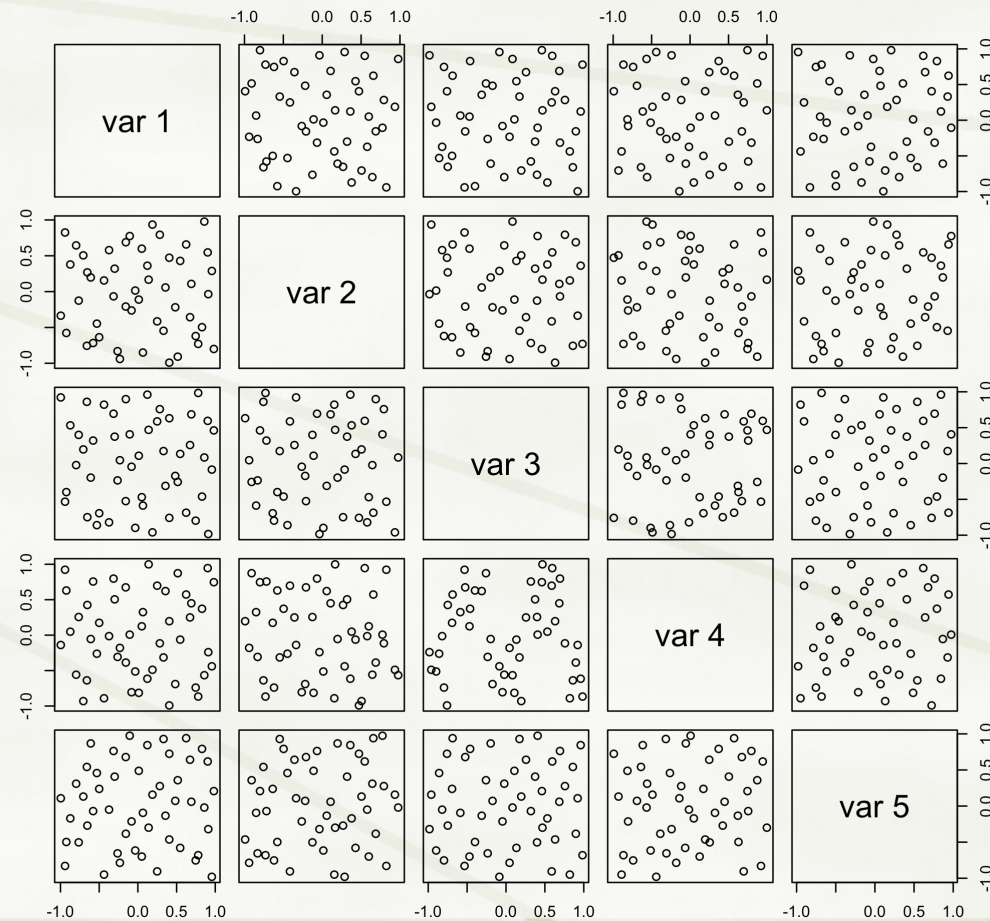


Defect detection

- Low Discrepancy Sequences (LDS)

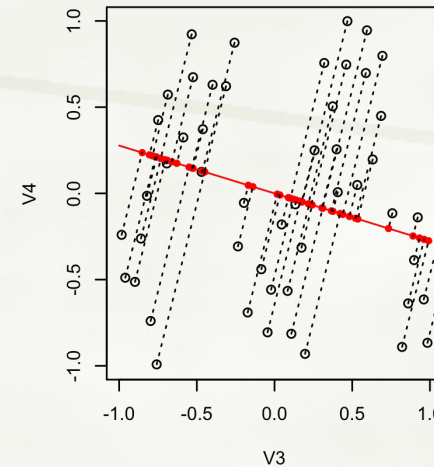
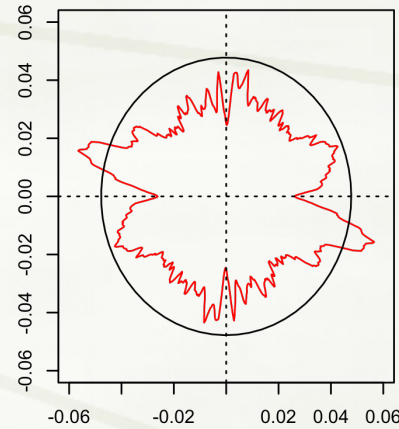
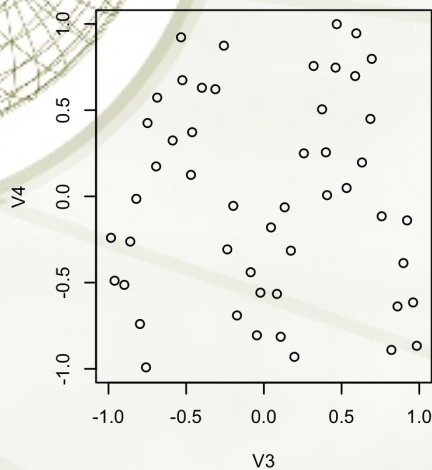
- Sobol

Owen
scrambling



Defect detection

- Low Discrepancy Sequences – 2D and 3D RSS

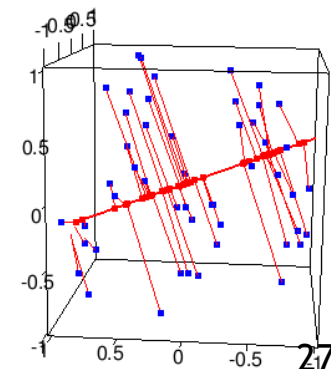


In 2D

- worst subspace : (3,4)
- worst direction $\approx (0.96, -0.26)$

In 3D

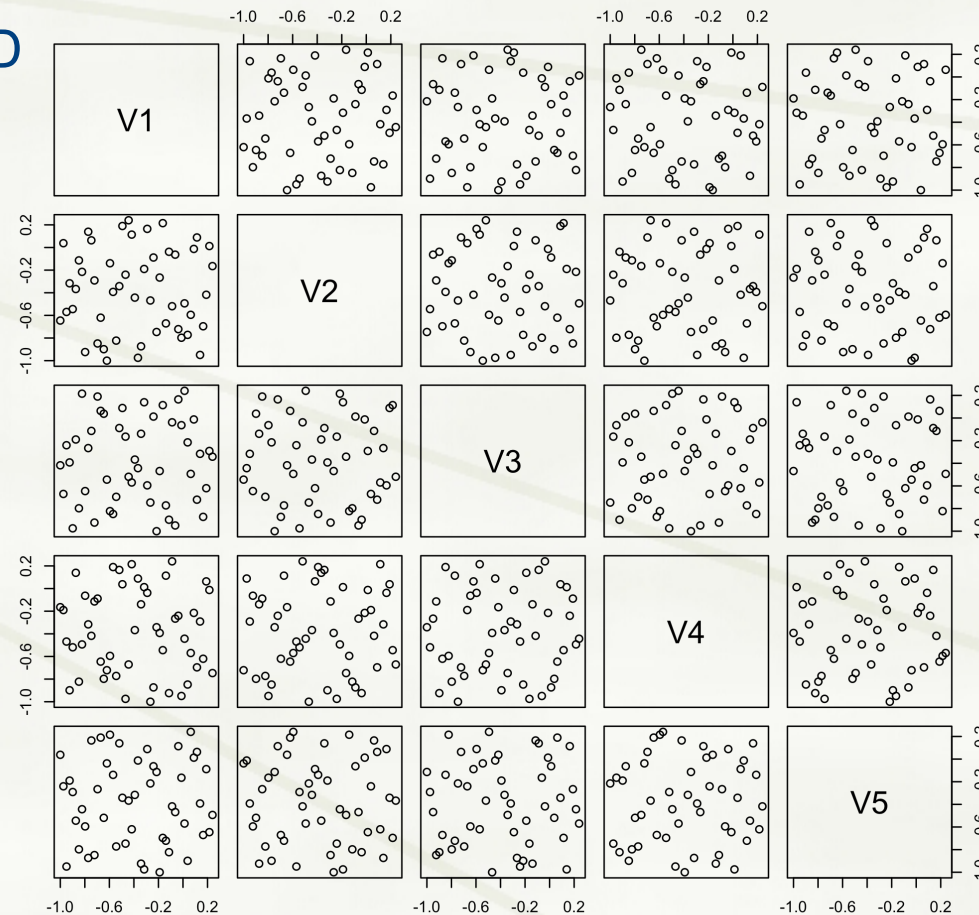
- worst subspace : (1,3,4)
- worst direction $\approx (-0.14, 0.93, -0.33)$



Defect detection

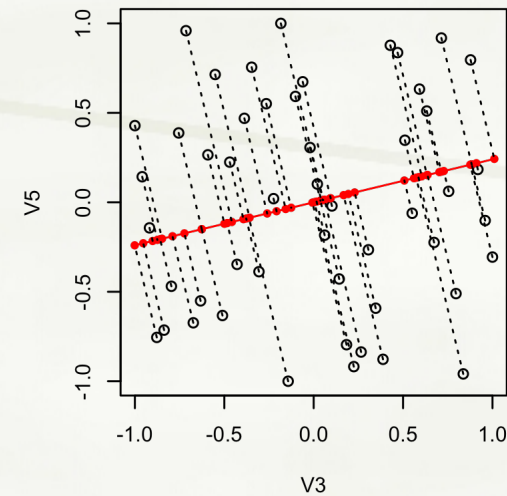
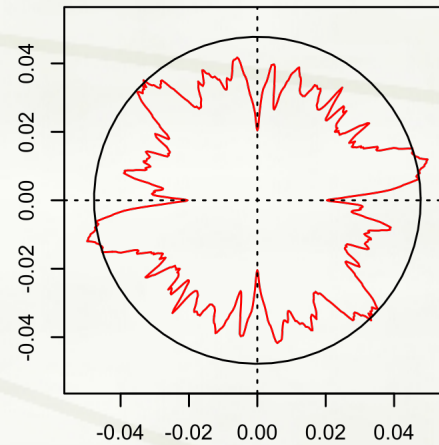
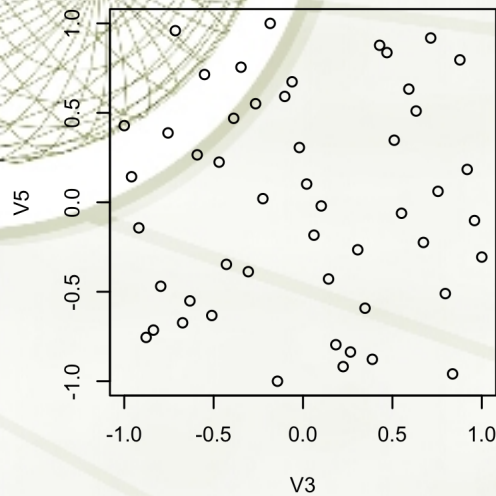
- Latin hypercube (LH) designs

- Maximin LHD



Defect detection

- Maximin LHD

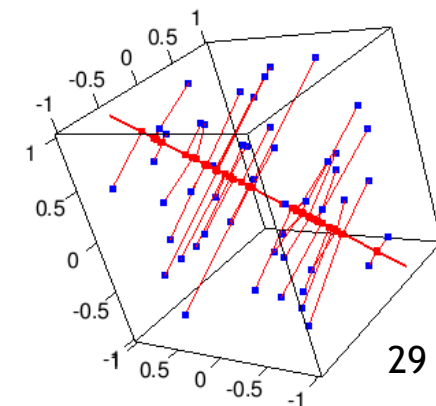


In 2D

- worst subspace : (3,5)
- worst direction $\approx (0.97, 0.23)$

In 3D

- worst subspace : (3,4,5)
- worst direction $\approx (-0.31, 0.69, 0.64)$



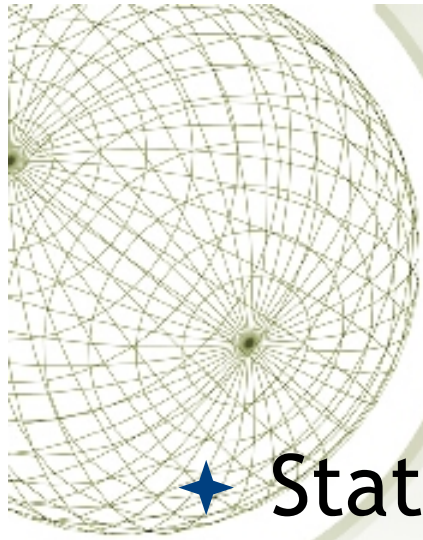
Selection of SFDs

- Comparison of 8D SFDs of size 80

Table 1 Worst value of Greenwood statistic for 8-dimensional SFDs of size 80

Design type ^a	Statistic value ^b
Uniform	0.039 (0.003)
Maximin Latin hypercube	0.048
Audze-Eglais Latin hypercube	0.037
Halton sequence	0.244
Faure sequence	0.161
Sobol sequence	0.101
Sobol sequence, with Owen scrambling	0.041 (0.006)
Sobol sequence, with Faure-Tezuka scrambling	0.088 (0.010)
Sobol sequence, with Owen + Faure-Tezuka scrambling	0.041 (0.006)
Strauss	0.040 (0.004)

^a LHDs are taken from <http://www.spacefillingdesigns.nl>. Halton and Sobol sequences are computed with the R package randtoolbox (<http://www.r-project.org>). ^b For stochastic designs, the first number is the mean of the results over 100 simulations, and the second (into brackets) their standard deviation.



Future research

- ★ Statistical issue
- ★ Higher dimensions

A decorative wireframe sphere is located in the top-left corner of the slide. It is composed of a grid of intersecting lines, creating a 3D effect. The sphere is positioned partially behind the title and the first bullet point.

Decisional issues

- Multiple testing framework
 - multiple pairs (triplets) of dimensions
 - multiple angles
 - strong correlation !
- Partial solution
 - consider a global statistic over directions, such as: **sup/inf**
 - ➔ the multiple testing issue over dimensions remains...

A decorative wireframe sphere is located in the top-left corner of the slide. It is composed of a grid of lines forming a spherical shape, with a small dot at its center.

Future research

- Radial scanning in higher dimensional subspaces
 - Visualization is no longer possible
 - Computational cost
 - ➔ Optimization techniques
 - ➔ Normal approximations ? (away from factorial subspaces)
- Other ideas
 - Radial scanning of 2D (or higher) subspaces



Acknowledgements

We wish to thank A. Antoniadis, the members of the DICE Consortium (<http://www.dice-consortium.fr>), the participants of ENBIS-DEINDE 2007, as well as two referees for their useful comments. We also thank Chris Yukna for his help in editing.

THANK YOU FOR YOUR ATTENTION